

Procedural Semantics

Soundness of SLD-Resolution

Propositions:

Let θ, ρ, γ be substitutions, E an expression.

$$\theta \varepsilon = \varepsilon \theta = \theta \quad (\text{Identity})$$

$$(E\theta)\rho = E(\theta\rho)$$

$$(\theta\rho)\gamma = \theta(\rho\gamma) \quad (\text{Associativity})$$

Proof:

Follows from definition of ε

prove proposition for $E=x$

prove $E(\theta\rho)\gamma = E\theta(\rho\gamma)$ for $E=x$ and 2.

Example

Definition:

Let S be a finite set of simple expressions. A Substitution θ is called a *unifier* for S , if $S\theta$ is a singleton.

A unifier θ is called a *most general unifier (mgu)* for S if, for each unifier ρ of S there exists a substitution γ such that $\rho = \theta\gamma$.

Example

Note: If there exist two mgu's then they are variants.

Definition:

Let S be a finite set of simple expressions. Locate the leftmost symbol position at which not all expressions in S have the same symbol and extract from each expression in S the subexpression beginning at that symbol position. The set of all such subexpressions is the *disagreement set*.

Example:

Let $S = \{p(f(x), h(y), a), p(f(x), z, a), p(f(x), h(y), b)\}$, then the disagreement set is $\{h(y), z\}$

1. put $k:=0$ and $\rho_0:=\varepsilon$
2. If S_{ρ_k} is a singleton, Then return(ρ_k)
Else find the disagreement set D_k of S_{ρ_k}
3. If there exist a variable v and a term t in D_k such that v does not occur in t ,
 // non-deterministic choice
 Then put $\rho_{k+1} := \rho_k\{v/t\}$, $k++$, goto 2
 Else exit // S is not unifiable

$\rho_0 = \varepsilon$, $k=1$

$S_{\rho_0} = \{\text{even}(0), \text{even}(y)\}$

$D_0 = \{0, y\}$

choose variable y , term 0

put $\rho_1 := \varepsilon\{y/0\}$, $k=1$

$S_{\rho_1} = \{\text{even}(0)\}$

return.

Theorem:

Let S be a finite set of simple expressions. If S is unifiable, then the unification algorithm terminates and gives a mgu for s . If S is not unifiable, then the unification algorithm terminates and reports this fact.

Proof Sketch:

Assume θ is a unifier for S . Show that until termination for all k :

$$\theta = \rho_k \gamma_k$$

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Assume θ is a unifier for S . Show that until termination for all k :

$$\theta = \rho_k \gamma_k$$

Induction start: $\rho_0 = \varepsilon, \gamma_0 = \theta$

From k to $k+1$ (we only need to consider S_{ρ_k} , because otherwise, we are done):

$$|S\theta| = 1 \Rightarrow |D\gamma_k| = 1$$

Pick a variable v and a term t , then:

- ◆ $v\gamma_k = t\gamma_k$
- ◆ $\rho_{k+1} = \rho_k\{v/t\}$
- ◆ $\gamma_{k+1} = \gamma_k \setminus \{v/v\gamma_k\}$, i.e. if v is bound in γ_k then
 - $\gamma_k = \{v/v\gamma_k\} \cup \gamma_{k+1} = \{v/t\gamma_k\} \cup \gamma_{k+1} = \{v/t\gamma_{k+1}\} \cup \gamma_{k+1} = \{v/t\} \gamma_{k+1}$
 - $\theta = \rho_k \gamma_k = \rho_k\{v/t\} \gamma_{k+1} = \rho_{k+1} \gamma_{k+1}$

SLD-Resolution

- SLD: SL-resolution for definite clauses
- SL: Linear resolution with selection function

Definition:

Let G be $\leftarrow A_1, \dots, A_m, \dots, A_k$

and C be $A \leftarrow B_1, \dots, B_q$.

Then G' is *derived* from G and C using mgu θ , if:

- a. A_m is an Atom, called the *selected* atom, in G
- b. θ is an mgu of A_m and A .
- c. G' is the goal $\leftarrow (A_1, \dots, B_1, \dots, B_q, \dots, A_k)\theta$.

In resolution terminology G' is called a *resolvent* of G and C .

Definition:

Let P be a definite program and G_0 a definite goal.

An *SLD-Derivation* of $P \cup \{G_0\}$ consists of a (finite or infinite) sequence G_0, G_1, G_2, \dots of goals, a sequence C_1, C_2, \dots of variants of program clauses of P and a sequence

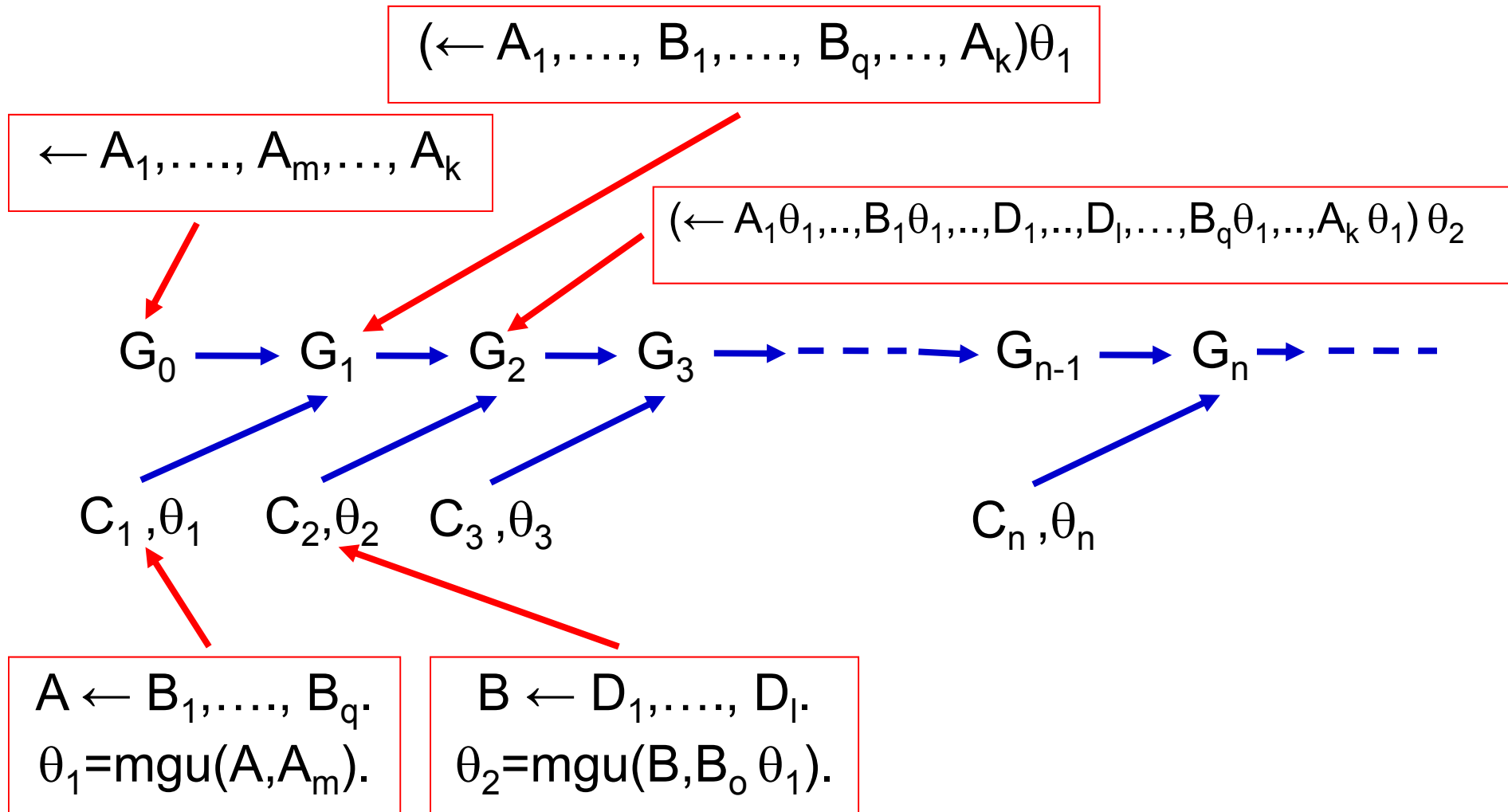
$\theta_1, \theta_2, \dots$ of mgu's such that each G_{i+1} is derived from G_i and C_{i+1} using θ_{i+1} .

standardising apart the variables:

subscribe all variables in C_i with i .

Otherwise $\leftarrow p(x)$ could not be unified with $p(f(x)) \leftarrow$.

each program clause variant C_1, C_2, \dots is called an *input clause* of the derivation



Program P
 1 $Q(x) :- R(g(x)).$
 2 $R(y).$

Goal: $Q(f(z)).$

$\leftarrow Q(f(z))$

$\leftarrow R(g(f(z))).$

$G_0 \rightarrow G_1 \rightarrow \square$

Computed Answer
 $\{x/f(z), y/g(f(z))\}$ restricted to
 variables of $Q(f(z))$ results in
 ε

C_1, θ_1 C_2, θ_2

$Q(x) :- R(g(x)).$
 $\theta_1 = \text{mgu}(Q(x), Q(f(z)))$
 $= \{x/f(z)\}$

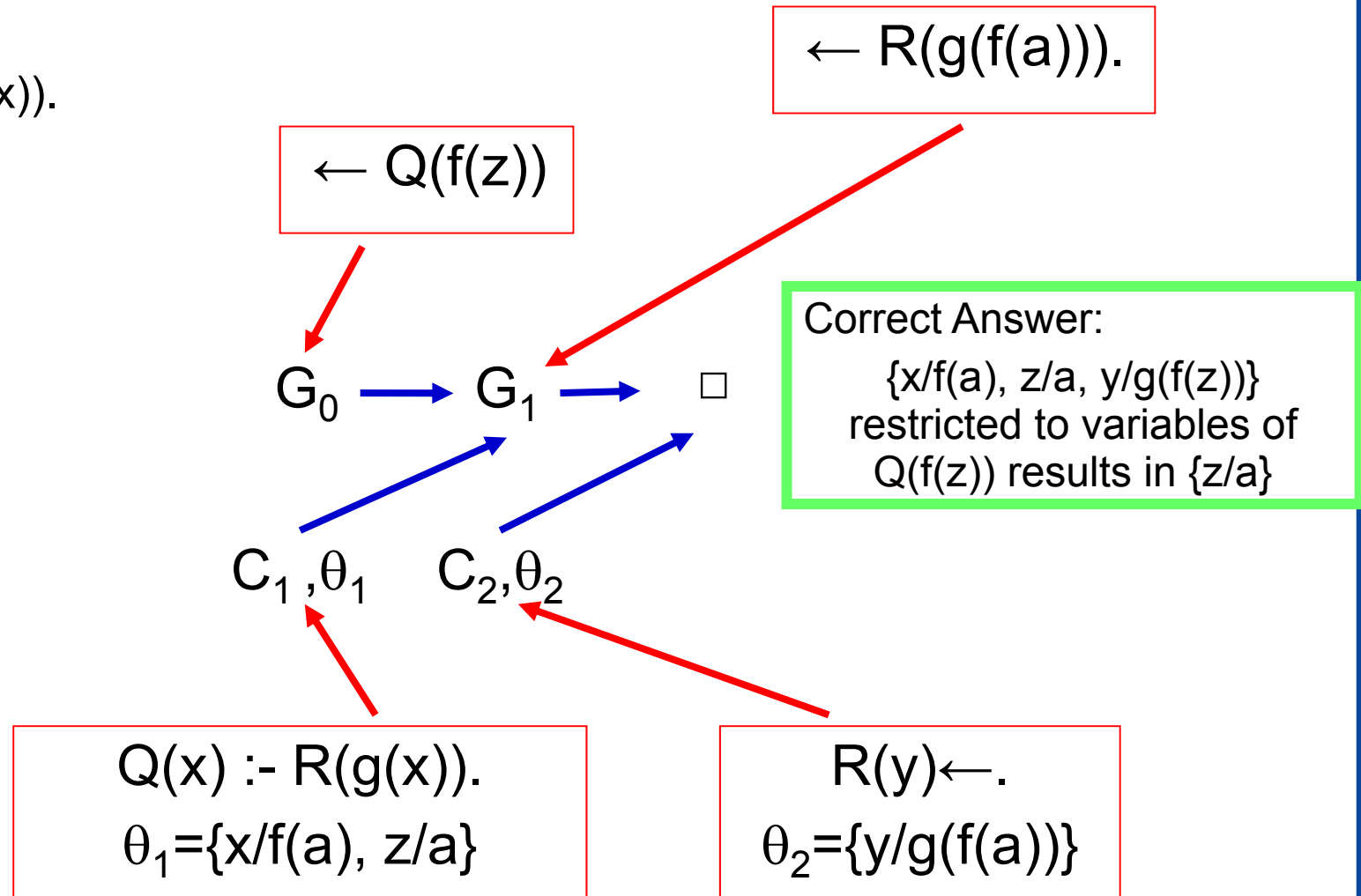
$R(y) \leftarrow.$
 $\theta_2 = \text{mgu}(R(y), R(g(f(z))))$
 $= \{y/g(f(z))\}$

Example – Unrestricted SLD-Refutation

unrestricted \rightarrow unifiers need not be mgu's

Program P
 1 $Q(x) :- R(g(x)).$
 2 $R(y).$

Goal: $Q(f(z)).$



Definition:

An *SLD-refutation* of $P \cup \{G\}$ is a finite SLD-derivation of $P \cup \{G\}$, which has \square as the last goal in the derivation. If $G_n = \square$, we say the refutation has *length* n .

SLD-derivations can be *finite* or *infinite*.

A finite SLD-derivation can be *successful* or *fail*.

An SLD-derivation is successful, if it ends in \square .

An SLD-derivation is *failed*, if it ends in a non-empty goal, which cannot be unified with the head of a program clause.

Definition:

Let P be a definite program.

The *success set* of P is the set of all $A \in B_P$ such that $P \cup \{\leftarrow A\}$ has an SLD-refutation.

Procedural Counterpart of the
Least Herbrand Model!

Definition:

Let P be a definite program and G a definite goal. Let $\theta_1 \dots \theta_n$ be the sequence of mgu's used in an SLD-refutation of $P \cup \{G\}$.

A *computed answer* θ for $P \cup \{G\}$ is the substitution obtained by restricting the composition $\theta_1 \dots \theta_n$ to the variables of G .

goal:

$\leftarrow \text{sort}(17.22.6.5.\text{nil}, y)$

computed answer:

$\{y/5.6.17.22.\text{nil}\}$

$\text{sort}(x,y) \leftarrow \text{sorted}(y), \text{perm}(x,y)$
 $\text{sorted}(\text{nil}) \leftarrow$
 $\text{sorted}(x.\text{nil}) \leftarrow$
 $\text{sorted}(x.y.z) \leftarrow x \leq y, \text{sorted}(y.z)$
 $\text{perm}(\text{nil}, \text{nil}) \leftarrow$
 $\text{perm}(x.y, u.v) \leftarrow \text{delete}(u, x.y, z), \text{perm}(z, v)$
 $\text{delete}(x, x.y, y) \leftarrow$
 $\text{delete}(x, y.z, y.w) \leftarrow \text{delete}(x, z, w)$
 $0 \leq x \leftarrow$
 $f(x) \leq f(y) \leftarrow x \leq y.$

Theorem

Let P be a definite program and G a definite goal. Then every computed answer for $P \cup \{G\}$ is a correct answer for $P \cup \{G\}$.

Proof

Let G be the goal $\leftarrow A_1, \dots, A_k$ and $\theta_1 \dots \theta_n$ the sequence of mgu's in a refutation of $P \cup \{G\}$.

Show that $\forall ((A_1, \dots, A_k) \theta_1 \dots \theta_n)$ is a logical consequence of P using induction (starting at the last goal) over the length of the derivation.

Corollary

The success set of a definite program is contained in its least Herbrand model.

Proof

Let the program be P , let $A \in B_P$ and suppose $P \cup \{\leftarrow A\}$ has a refutation. By the theorem on the prior slide A is a logical consequence of P . Thus A is in the least Herbrand model of P .

- **strengthen this corollary**

If $A \in B_p$ and $P \cup \{\leftarrow A\}$ has a refutation of length n ,
then $A \in T_p \uparrow n$.

- **Notation**

$[A] = \{A' \in B_p : A' = A\theta \text{ for some substitution } \theta\}$

- Not treated this year, check out
- <http://isweb.uni-koblenz.de/Teaching/SS08/adm08>